# **Global Lake Surface Water Temperatures from ATSR**

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## Introduction

Lakes are a vital component of Earth's fresh water resources, and are of fundamental importance for terrestrial life. Lake water temperature is one of the key parameters determining ecological conditions within a lake and airwater heat and moisture exchanges. Lake surface water temperatures (LSWT) and lake ice cover (LIC) observations therefore have potential environmental and meteorological applications for inland water management and numerical weather prediction (NWP).

The European Space Agency (ESA) have established the ARC-Lake project (www.geos.ed.ac.uk/arclake) to adapt sea surface temperature (SST) techniques for cloud and ice detection and for surface temperature retrieval to the problem of lakes.

The ARC-Lake project considers "large" natural lakes (surface area > 500 km<sup>2</sup>). A small number of additional lakes/reservoirs are included where they are of scientific interest and/or have validation data available or have been requested by the ARC-Lake User Group. The locations of these lakes are shown in Figure 1.





Figure 2. GLWD polygon for Astray Lake, Canada and resulting binary lake mask in Google Earth.

# Lake Mask

Attributing observations to individual lakes is not a trivial task. Lake-inflow, lake-outflow, lake-lake and/or lake-ocean boundaries need to be defined. Lakes may also have complex shapes, such as Astray Lake, Canada (Figure 2.). To overcome these issues, we defined a new lake mask based on existing land/water masks and individual lake polygons from the Global Lakes and Wetland Database (GLWD).

NAVOCEANO and Envisat masks were assessed a potential source. NAVOCEANO was selected as it offered higher levels of and accuracy of coverage. Figure 3. illustrates this for the example of Lake Abaya, Ethiopia, where the Envisat mask locates the lake to the east of its true location.

### 3

# **Cloud Detection and LSWT Retrieval**

Cloud detection is a key element of LSWT retrieval, and inadequacies in detection give rise to significant uncertainties. In ARC-Lake we adopt a Bayesian approach informed by forward modelling, rather than a threshold based approach (e.g. SADIST).

Fig. 4. (a) and (b) illustrates the largely successful performance of this method, with all obviously cloudy areas flagged as cloud. Some clear-sky areas are incorrectly flagged as cloud. However, the rate of false positive detections is significantly less than with threshold based cloud screening. ARC-Lake LSWT retrievals use optimal estimation (OE) methods. Again, this incorporates forward-modelling, for which RTTOV8.7 is used. NWP data from ECMWF are used as the priors in the forward modelling, except for the LSWT field, due to inaccuracies in the NWP data for LSWT. EOF-based methods are applied to the ARC-Lake observations to create a spatially complete prior LSWT field, demonstrated in Fig. 4. (c). Comparison with the subsequent night-time observations (Fig. 4. (d)) reveals these methods are able to accurately reconstruct the LSWT field.



Figure 3. Envisat (left) and NAVOCEANO (right) masks for Lake Abaya, Ethiopia. Red overlay = correctly classed as water.





Attribute	Pos
Coverage	Per
Source	Obs Rec
Time	Day
Spatial Resolution	0.05 / La
Temporal Averaging	Nor Clin Tim
Temporal Averaging Period	Sea Mo moi



